


7.3. 交流电

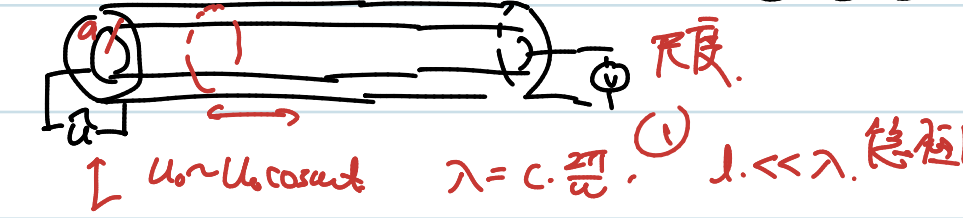
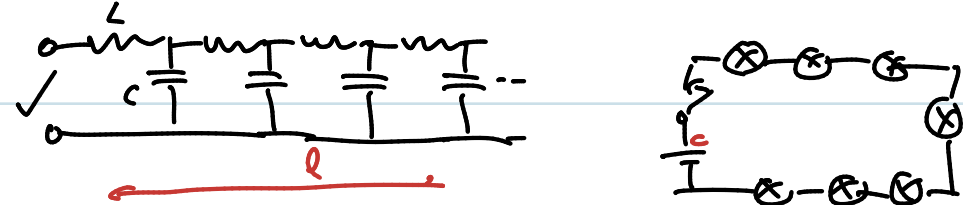
C.L., $C \frac{du}{dt} = \frac{dq}{dt} = I$. $\lambda \gg l$.
 $\Rightarrow \int U \cdot I \propto e^{i\omega t} \frac{d}{dt} \rightarrow i\omega$ 稳态/暂态

\hat{u}_i  $\tilde{z}_c = \frac{\hat{u}_i}{i\omega C + R}$ \leftarrow 由Q定
 $U_0 \cos \omega t = \frac{Z_L + Q(\omega) + IR}{C}$
 $- \omega U_0 \sin \omega t = \frac{Z}{C} + iR$

$Z(t) = \frac{U_0 \cos(\omega t + \varphi)}{iR + \frac{1}{i\omega C}} + Z_L(t)$
 $Z_L + iR = 0$. $Z_L = A e^{-\frac{t}{R}}$

设稳态. $C \rightarrow \frac{1}{i\omega C}$. $L \rightarrow i\omega L$ 直流电路都可以用

有的还会不同

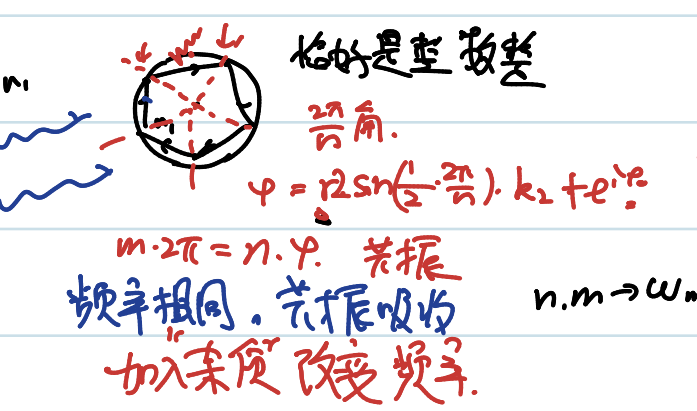
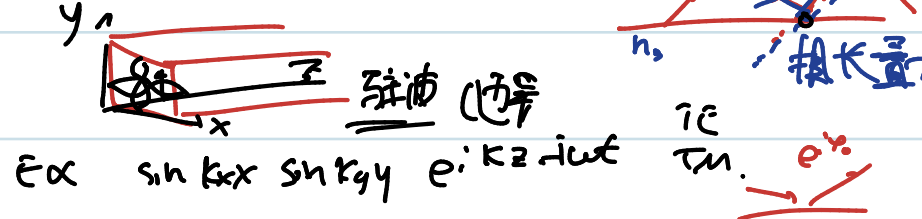


(2) $a \ll \lambda \ll d$. 每一小段上几乎同相位.

在局域稳恒. $C \rightarrow \frac{1}{i\omega C}$. $L \rightarrow i\omega L$

整体看, 不是, 形变传播.

(3) $\lambda \sim a$. $\lambda \ll d$ 波导

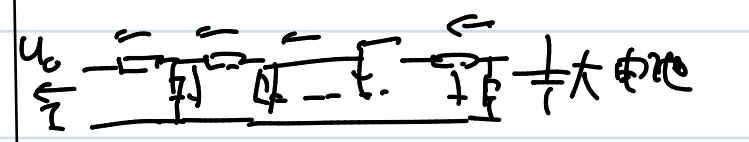


$r = \frac{n_1 \cos \theta_1 - n_2 \cos \theta_2}{n_1 \cos \theta_1 + n_2 \cos \theta_2} = 1 \cdot e^{i\varphi}$ n 个格子
 全反射. $\cos \theta_2 = \sqrt{1 - \sin^2 \theta_2}$
 $= \sqrt{1 - \frac{n_1^2 \sin^2 \theta_1}{n_2^2}}$

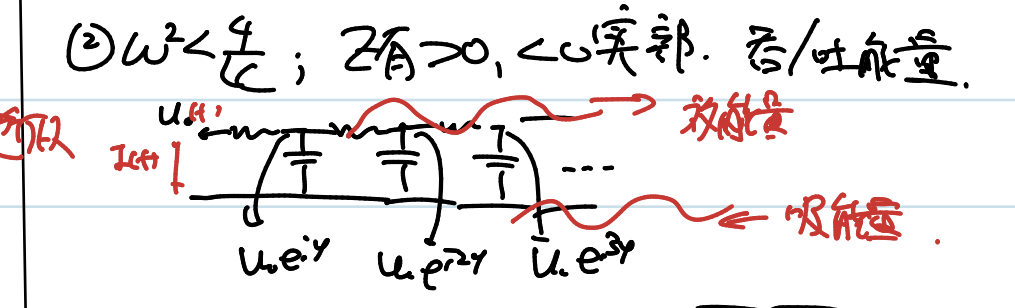
$\frac{1}{Z} = \frac{1}{i\omega L} + \frac{1}{Z} = \frac{1}{Z}$
 $Z = i\omega L + \frac{Z}{Z + \frac{1}{i\omega C}}$
 $R = \frac{-iZ\beta}{Z}$ 取正.

$Z^2 + Z \frac{1}{i\omega C} = i\omega L Z + \frac{1}{i\omega C} Z$
 $Z^2 - i\omega L Z - \frac{1}{i\omega C} = 0 \Rightarrow Z = \frac{i\omega L \pm \sqrt{\omega^2 L^2 - \frac{4}{C}}}{2}$
 (1) $\omega^2 > \frac{4}{LC}$. Z 虚. $Z_{\pm} = \frac{i\omega L \pm i\sqrt{\omega^2 L^2 - \frac{4}{C}}}{2}$ 取哪?

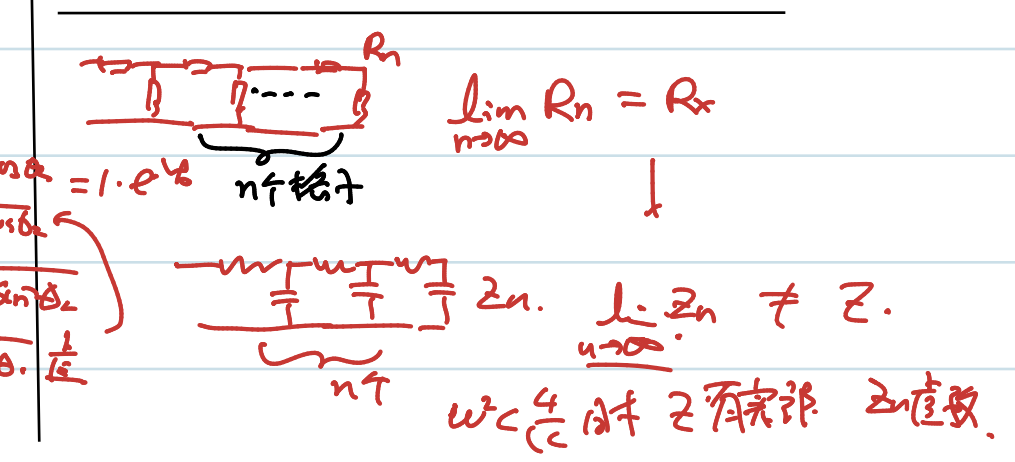
(2) $\omega^2 < \frac{4}{LC}$. $Z = \frac{i\omega L \pm \sqrt{\omega^2 L^2 - \frac{4}{C}}}{2}$. 正或负实部
 负根 $R = \frac{1-\beta}{2}$. 代表基于霍夫另个根
 \rightarrow 指数放大根.

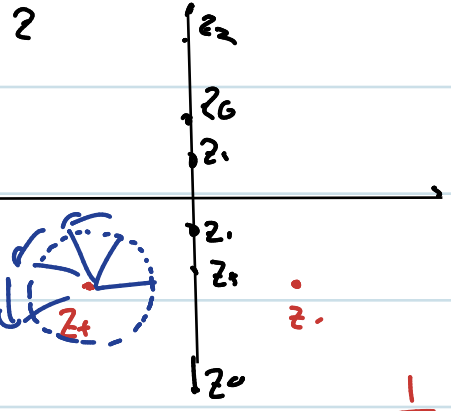


(1) Z_{\pm} 代表振幅 指数变大或指数变小的解
 $U_0 \frac{\lambda U_0}{C} \frac{\lambda U_0}{C} \frac{\lambda U_0}{C}$ $\lambda > 1$. $\lambda < 1$
 对应 Z_{\pm} . 取哪

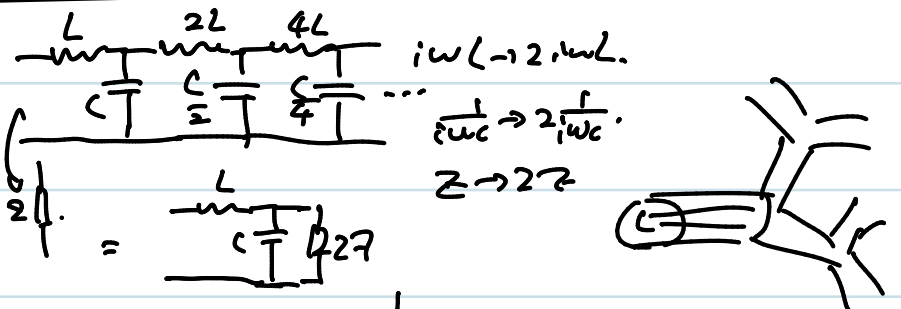


$P(t) = U(t) I(t) = Z \cos(\omega t) \cdot |Z| \cos(\omega t + \varphi)$
 $= \frac{1}{2} |Z|^2 \omega \cos(\varphi)$. $= \frac{1}{2} \text{Re}[\hat{U} \hat{I}^*]$
 Z 有实部, 实部 > 0 $P(t) > 0$ 发射能量
 虚部 < 0 $P(t) < 0$ 吸收.





先解得 z_n
 $z_{n+1} = i\omega L + \frac{\frac{1}{i\omega C} z_n}{z_n + \frac{1}{i\omega C}}$
 令 $z_{n+1} = \frac{b_{n+1}}{a_{n+1}}$ 代入...
 $b_n =$ 阶数 阶数...
 \rightarrow 落在一个圆上. 等角度转动.
 Abel 极限下落在圆上.



$i\omega L \rightarrow 2i\omega L$
 $\frac{1}{i\omega C} \rightarrow 2\frac{1}{i\omega C}$
 $z \rightarrow 2z$

$$z = i\omega L + \frac{2z \frac{1}{i\omega C}}{2z + \frac{1}{i\omega C}}$$

$$2z^2 + z \frac{1}{i\omega C} = i\omega L \cdot 2z + \frac{L}{C} + 2z \frac{1}{i\omega C}$$

$$2z^2 + (-\frac{1}{i\omega C} - 2i\omega L)z - \frac{L}{C} = 0$$

$$z = \frac{2i\omega L + \frac{1}{i\omega C} \pm \sqrt{(\frac{1}{i\omega C} + 2i\omega L)^2 + 4\frac{L}{C}}}{2}$$

有解即 有能量. 传播波. $\frac{4L}{C} > (\frac{1}{i\omega C} + 2i\omega L)^2$



变成带通.

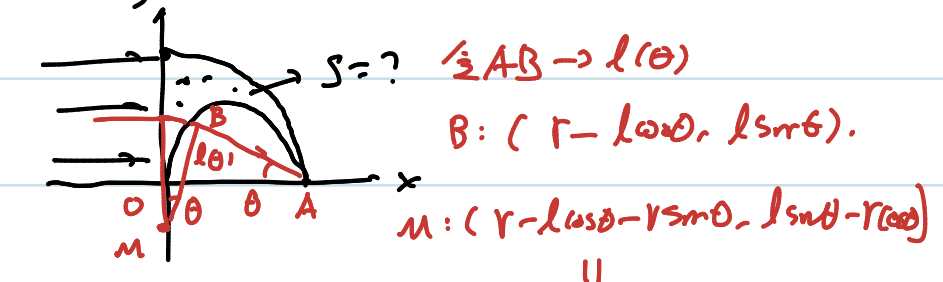
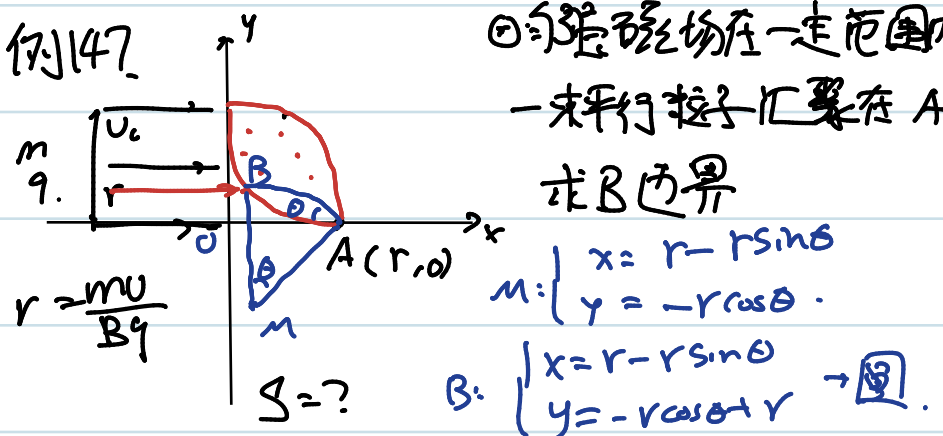
$z(L_i, L_i) = z(\frac{L_i}{\omega C_i}, \omega L_i)$ 互值.
 $= \omega L_i \cdot z(\frac{L_i}{L_i}, \frac{1}{\omega^2 C_i L_i})$

第一级 $\omega L_1 \cdot z(\frac{L_1}{C_1}, \frac{1}{\omega^2 C_1 L_1})$
 第二级 $\omega L_2 \cdot z(\frac{L_2}{C_2}, \frac{1}{\omega^2 C_2 L_2})$
 $\frac{L_i}{C_i}$ 级. $\frac{C_i}{L_i}$ 级
 $f(x) = z(\frac{1}{\omega C_i L_i})$
 令 $z = i\omega L_i f(x)$ 第二级: $z' = 2i\omega L_i f(\frac{x}{2})$
 $\Rightarrow i\omega L_i f(x) = i2\omega L_i + \frac{\frac{1}{i\omega C_i} \cdot 2i\omega L_i f(\frac{x}{2})}{\frac{1}{i\omega C_i} + 2i\omega L_i f(\frac{x}{2})}$
 $x = \frac{1}{\omega^2 C_i}$

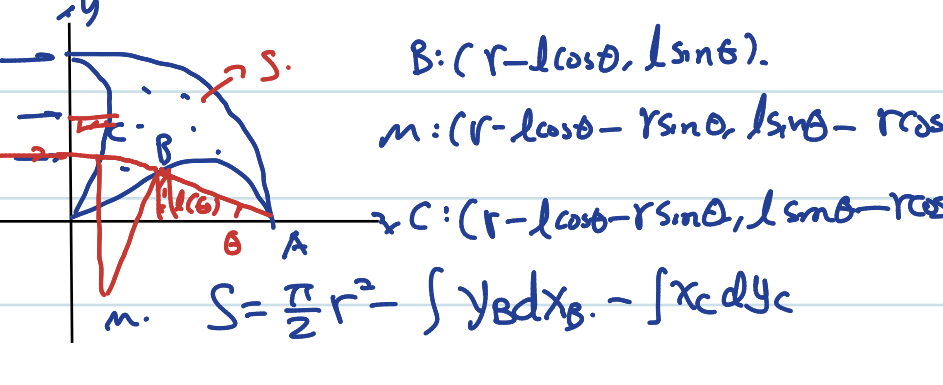
$i\omega L_i f(x) = i2\omega L_i + \frac{\frac{1}{i\omega C_i} \cdot 2i\omega L_i f(\frac{x}{2})}{\frac{1}{i\omega C_i} + 2i\omega L_i f(\frac{x}{2})}$
 $x = \frac{1}{\omega^2 C_i}$
 $f(x) = 2 + \frac{2 f(\frac{x}{2})}{1 - 2 \frac{1}{x} f(\frac{x}{2})}$
 令 $f(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$ 高次展开.

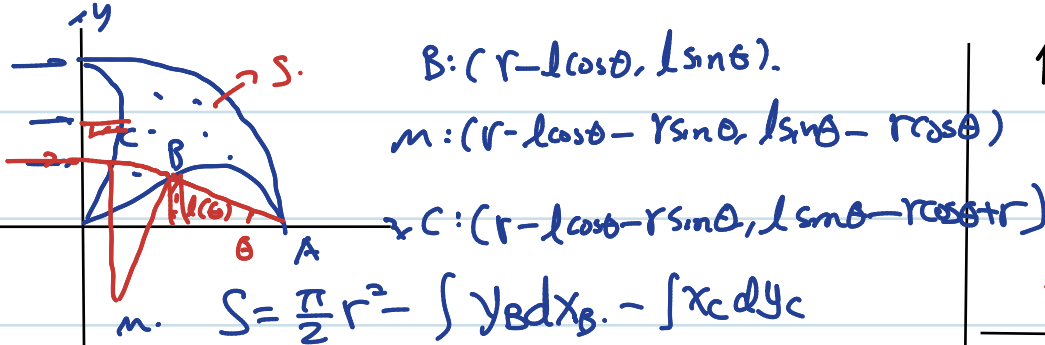
8. 磁场中带电粒子运动

图同.



$r - l \cos \theta - r \sin \theta = 0; l = \frac{r(1 - \sin \theta)}{\cos \theta}$
 $B: (r \sin \theta, \frac{r(1 - \sin \theta) \sin \theta}{\cos \theta})$
 $S = \frac{\pi}{2} r^2 - \int_{\theta=0}^{\theta=\pi/2} y_B dx_B$
 $= \frac{\pi}{2} r^2 - \int_0^{\pi/2} \frac{r(1 - \sin \theta) \sin \theta}{\cos \theta} \cdot dr \sin \theta d\theta$
 $r^2 \int_0^{\pi/2} (\sin \theta - \sin^2 \theta) d\theta$
 $= \frac{\pi}{2} r^2 - r^2 \cdot (1 - \frac{1}{2} \cdot \frac{\pi}{2})$ 同个面积.





$B: (r \cos \theta, r \sin \theta)$
 $m: (r \cos \theta - r \sin \theta, r \sin \theta - r \cos \theta)$

$c: (r \cos \theta - r \sin \theta, r \sin \theta - r \cos \theta)$

$S = \frac{\pi}{2} r^2 - \int y dx_B - \int x dy_C$

$\int q_B dx_B + \int x dy_C$
 $= \int_0^{\pi/2} [r \sin \theta d(-r \cos \theta) + \int_0^{\pi/2} [r(1 - \sin \theta) - r \cos \theta] d[r \sin \theta - r \cos \theta]$
 分开. l^2 . $l r$. r^2

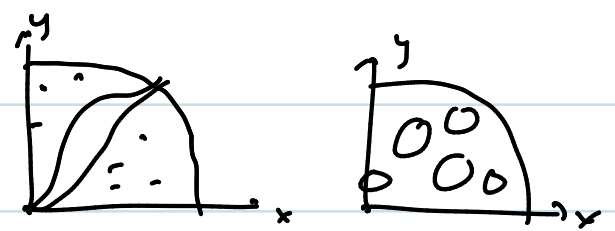
$l^2: \int_0^{\pi/2} r \sin \theta d(-r \cos \theta) + \int_0^{\pi/2} (-r \cos \theta) d[r \sin \theta - r \cos \theta]$
 $= \int_0^{\pi/2} r d[-r \cos \theta \sin \theta]$

$l r: \int r(1 - \sin \theta) d[r \sin \theta] + \int (-r \cos \theta) d(-r \cos \theta)$

$= \int r(1 - \sin \theta) d[r \sin \theta] + \int +1 \cdot \sin \theta d[r \sin \theta + r]$ 例149

$= \int_0^{\pi/2} d[r \sin \theta r(1 - \sin \theta)] \rightarrow 0$

$r^2: \int_0^{\pi/2} r^2(1 - \sin \theta) \sin \theta d\theta$ 与(1)相同.



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7.2 其它(2)力

$\vec{F} = q \vec{U} \times \vec{B} +$

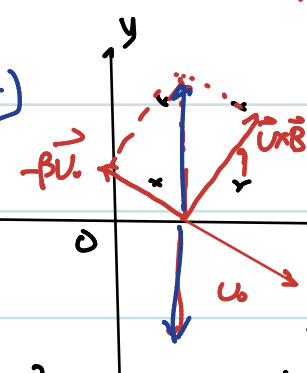
- ① 线性 齐性/非齐性
 $-k \vec{r}, -\beta \vec{U}, +m \vec{g}$
 $-\beta \vec{U} + m \vec{g}$
 猜指数解.

- ② 自然坐标 $-f(u) \hat{U}$
 拆成切/法.

- ③ 多一个守恒量, 正则动量
 连续对称. 正则角动. 组合

① 线性.

例148 $\vec{F} = m \vec{a} = q \vec{U} \times \vec{B} - \beta \vec{U} + m \vec{g}$



$\hat{U} = \hat{U}(t) + \hat{U}$
 $q \vec{U} \times \vec{B} - \beta \vec{U} + m \vec{g} = 0$

$m \dot{\vec{U}}(t) = q \vec{U} \times \vec{B} - \beta \vec{U}$
 平面 -> 复数 $\tilde{U} = U_x + i U_y$

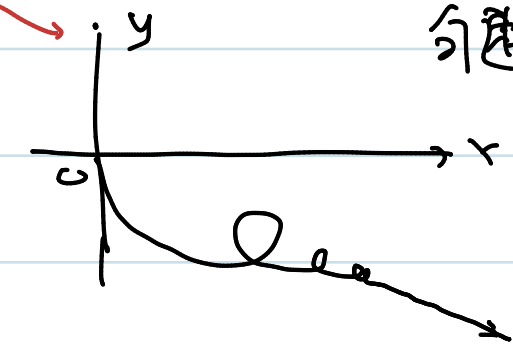
$m \dot{\tilde{U}} = (i q B - \beta) \tilde{U}$

$\tilde{U}_i = \tilde{A} \cdot e^{(i q B - \beta) t}$

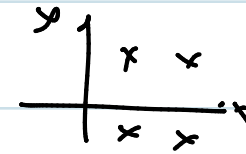
半径指数减小

匀速率加.

缩小. 圆周.



例149 $m \vec{a} = q \vec{U} \times \vec{B} + \vec{F}_0 \cdot \hat{n}(t)$



$\hat{n}(t) = (\cos \omega t, \sin \omega t)$

$m \vec{a} = q \vec{U} \times \vec{B} \Rightarrow \dot{\vec{U}} = \vec{a} e^{i q B t}$

猜 $\vec{U} = \vec{U}_i e^{i \omega t} + \vec{A}$

$m i \omega \vec{U}_i e^{i \omega t} = i q B \vec{U}_i e^{i \omega t} + \vec{F}_0 e^{i \omega t}$

$\vec{U}_i = \frac{\vec{F}_0}{i m \omega + q B}$

$\vec{U} = \vec{U}_i e^{i q B t} + \frac{\vec{F}_0}{i m \omega + q B} e^{i \omega t}$

两圆同(2)力叠加

行星(2)力.



例150 $m \vec{a} = q \vec{U} \times \vec{B} - f(u) \hat{U}$

$f(u) = -\beta U, -a_0, -b U^2$

$\vec{a} = \dot{U} \hat{U} + \omega U \hat{n}$

$\Rightarrow m \dot{U} \hat{U} + \omega U \hat{n} m = q B \hat{n} - f(u) \hat{U}$

$\omega = \frac{q B}{m}, \dot{U} = -\frac{f(u)}{m}; \int \frac{dU}{f(u)} = \int \frac{dt}{m}$

$v(t) \Rightarrow r = \frac{m U(t)}{B q}$

曲线中心只能沿曲线运动。

$$v_c = \frac{dr_c}{dt} = \frac{m\dot{u}}{Bq} = \frac{m\omega r}{Bq}$$

法向与切向一样，均有瞬时变化

$$\vec{v}_c = \frac{m\omega r}{Bq} [\cos(\omega t + \varphi), \sin(\omega t + \varphi)]$$

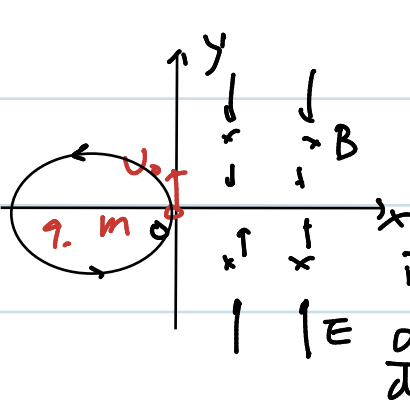
定轨迹。物体轨迹是曲线中心轨迹的渐开线

例151. 加一个对称性。

$$\left[\frac{\partial L}{\partial q} = 0, \frac{d}{dt} \frac{\partial L}{\partial \dot{q}} = 0, \frac{\partial L}{\partial q} = p \Rightarrow \text{守恒} \right]$$

找一个方向平移/转动对称，写动量/角动量守恒

变成全微分 \Rightarrow 守恒量



$\vec{B} = B(-\hat{z})$ $\vec{E} = \hat{y} \cdot (-\alpha y)$

$\frac{1}{2} m v_x^2 + \frac{1}{2} m v_y^2 = \frac{1}{2} m v^2 - \frac{1}{2} q \alpha y^2$

沿x轴平移。

$\frac{dR_x}{dt} = -q \omega y B$; $dR_x = -q B \omega dy$

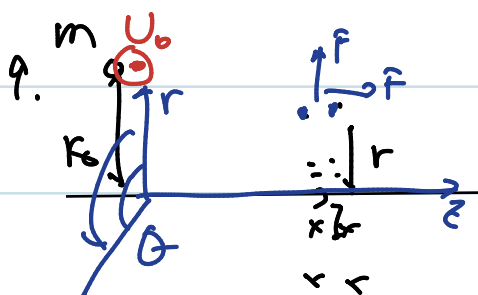
$$\Rightarrow d(R_x + qBy) = 0$$

$$R_x + qBy = 0 \Rightarrow R_x = -qBy \text{ 守恒}$$

$$\Rightarrow \frac{1}{2} m v_y^2 + \frac{1}{2m} q^2 B^2 y^2 + \frac{1}{2} \alpha q y^2 = \frac{1}{2} m v^2$$

y方向简谐。

$R_x = qBy \Rightarrow$ x方向简谐。



$B = \frac{\mu_0 I}{2\pi r}$

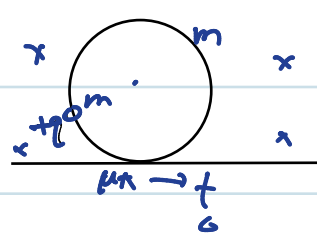
不在平面内运动

求 r_{max} 满足方程

$$\Delta E = 0 \text{ 柱平移+转动 } \left[\frac{1}{2} - q \frac{\mu_0 I}{2\pi} \ln r = C \right]$$

$$\Delta L = 0: \frac{dR_z}{dt} = q B(r) \frac{dr}{dt}$$

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正则动量守恒

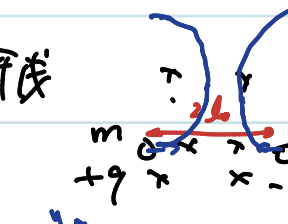
正则角动量

选择合适变量

例153

有磁作用 $\vec{r} \times \vec{B}$
不算磁能。求轨迹

$$t \rightarrow 0, U=0 \text{ 求}$$



x方向无库伦力。

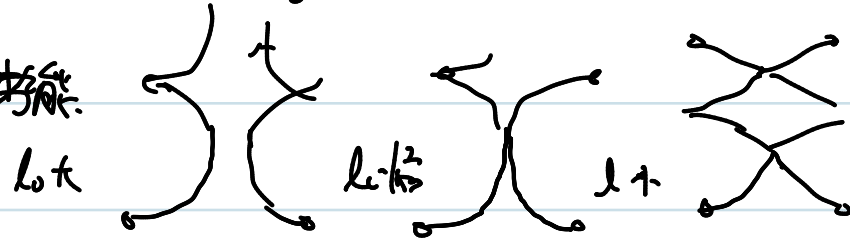
$$\frac{dR_x}{dt} = -q \omega y B$$

$$R_x + qBy = C = q l_0 B$$

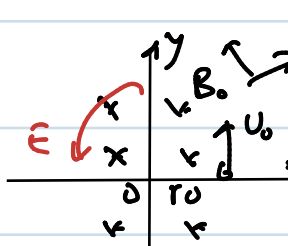
$$2 \times \left(\frac{1}{2} \frac{R_x^2}{m} + \frac{P_y^2}{2m} \right) - \frac{kq}{2y} = -\frac{kq}{2l_0}$$

$$\frac{R_x^2}{2m} + \frac{P_y^2}{2m} - \frac{kq}{4y} + \frac{kq}{4l_0} = 0$$

$$\left(q l_0 B - qBy \right)^2 - \frac{kq}{4y} + \frac{kq}{4l_0} + \frac{P_y^2}{2m} = 0 \quad y_{min}$$



8.3 浸渐不变量。



$r_0 = \frac{mU}{Bq}$

B_0 慢变为 $2B_0$ 时 $r \rightarrow ?$

$$\frac{dL}{dt} = \dot{r} q B \cdot r + E q \cdot r$$

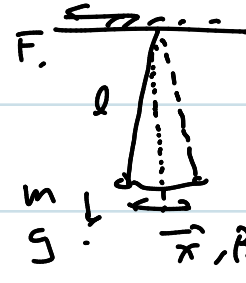
$$L = m v_0 r_0 = r \cdot r B q \rightarrow \frac{dL}{dt} = q B \frac{dr^2}{2dt} + q r \cdot \frac{dr^2 dB}{2r^2 dt}$$

$$\frac{dL}{dt} = \frac{d}{dt} \left[\frac{q B r^2}{2} \right]$$

$$d\left(\frac{1}{2} r^2 B q\right) = 0 \quad r^2 B q \rightarrow C \quad r \rightarrow \frac{1}{2} r_0$$

$$L - S = \pi r^2 \frac{q B q}{2\pi m} \propto L \text{ 不变}$$

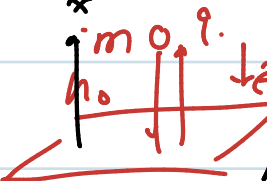
- 一个周期运动 $\oint p dq = I$
 - 参数慢变 $\frac{\Delta \lambda}{\lambda} \ll \frac{\lambda}{L}$
 $\Rightarrow I$ 不变

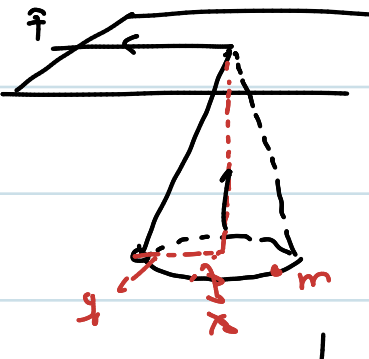
例 154. $l \rightarrow \frac{l}{2}, \omega \rightarrow ?$

 $x = l \theta_0 \cos \omega t$
 $p_x = -m \omega l \theta_0 \sin \omega t$
 $I = \pi \cdot l \theta_0 \cdot m \omega l \theta_0 = C$
 $l^2 \omega \theta_0^2 = C$
 $l^{\frac{3}{2}} g^{-\frac{1}{2}} \theta_0^2 = C$
 $l^{\frac{3}{2}} \theta_0^2 = C$

$E \rightarrow 2E, \theta \rightarrow ?$
 $\frac{l^{\frac{3}{2}}}{(Eg)^{\frac{1}{2}}} \theta^2 = C$
 $E^{-\frac{1}{2}} \cdot \theta^2 = C$

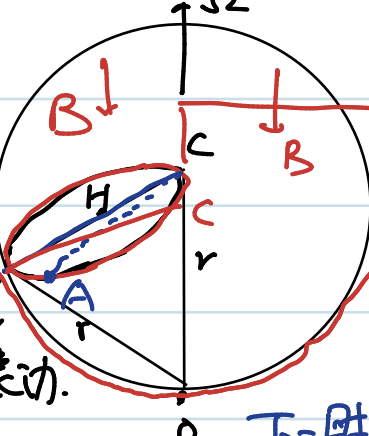
E 会变, 无势能项, 不能写 $\Delta E = 0$
 令 $E = E_0 + \alpha \frac{t}{T} E_0$ 代入, $\alpha \ll 1$, 微扰展开

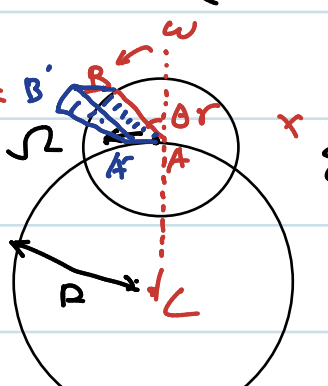
算一个周期
 $m \ddot{x} = -E_0 q (1 + \alpha \frac{t}{T}) x$
 $\alpha(\omega): x = A \cdot \cos \omega t, \omega = \frac{E_0 q}{m l}$
 $\alpha(1) x = A \cos \omega t \cdot (1 + \alpha f(\epsilon))$
 $-\omega^2 A \cos \omega t - A \cos \omega t \alpha f(\epsilon)$
 $= -\frac{E_0 q}{l} \cdot A \cos \omega t (1 + \alpha f(\epsilon))$
 $-\frac{E_0 q}{l} \alpha \frac{t}{T} \cdot A \cos \omega t$

x

 弹性
 $E_0 \rightarrow 2E_0$ 慢 $h_0 \rightarrow ?$
 $I = \oint p dq$
 $\propto h^{\frac{1}{2}} \epsilon^{\frac{1}{2}} q^2 m^{\frac{1}{2}}$

$\frac{y_0}{L} = \theta_0, \frac{x_0}{L} = \theta_{x_0}$

 抽绳子 $l \rightarrow \frac{l}{2}$
 $\theta \rightarrow ? \theta_{x_0} \rightarrow ?$
 $\int (p_x dx + p_y dy) = I$ 不变 ①
 L_z 守恒. ②

9 电磁感应
 9.1 动生 $\int q \vec{v} \times \vec{B} \cdot d\vec{l}$
 真实的原子实移动, 不是边界移动!
 对指定线路有定义, 不是对任意函数.

例 155. 公转角速度 Ω

 $\int_C \vec{v} \times \vec{B} \cdot d\vec{l} dt$
 $= \vec{B} \cdot \frac{d\vec{l} \times \vec{v} dt}{L ds}$
 回路面积变化不同.
 下两接触点不相切.
 取红色扫过面.
 $v = \omega' h \cdot \frac{\sqrt{3}}{2}$
 $\Sigma = \int U B \frac{\sqrt{3}}{2} dh$
 $= \frac{3}{4} \int_0^r \omega' h \cdot B dh$
 $= \frac{3}{4} \Omega \cdot B \frac{r^2}{2}$

例 176. 是真运动 $\int \vec{v} \times \vec{B} \cdot d\vec{l}$

 $\Sigma \rightarrow \frac{B \Delta S}{\Delta t} = B \cdot (\Omega R \cdot 2\pi R \Delta t + \frac{1}{2} \cdot \omega \cdot r^2)$



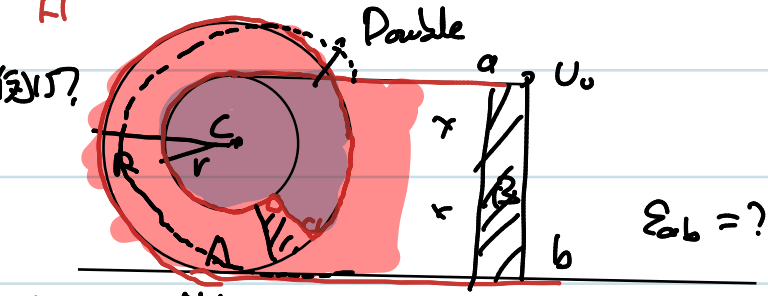
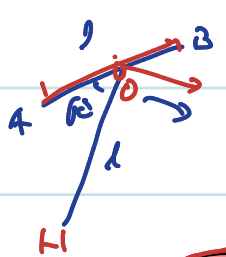
$$\vec{v}_m = \vec{v}_A + \vec{\omega} \times \vec{AM}$$

$$\int (\vec{v}_A + \vec{\omega} \times \vec{AM}) \times \vec{B} \cdot d\vec{r}_m$$

$$= \int \vec{v}_A \times \vec{B} \cdot d\vec{r}_m + \int (\vec{\omega} \times \vec{AM}) \times \vec{B} \cdot d\vec{r}_m$$

\downarrow $u_B r \cos \theta$ $\frac{1}{2} \omega r^2 B$

$$(\vec{\omega} \times \vec{HO}) \times \vec{B} \cdot \vec{AB}$$



①

$$u = u_0 \frac{R}{R+r}$$

$$\Delta S_1 = -u_0 \Delta t (r+R)$$

$$\Delta S_2 = \frac{1}{2} \omega \Delta t (R^2 - r^2)$$

$$\mathcal{E} = \frac{R \Delta S_1 + \Delta S_2}{\Delta t} = \left[-u_0 (r+R) + \frac{1}{2} \frac{u_0 R}{R+r} (R^2 - r^2) \right] B$$

②

$$\vec{v}_m = \vec{v}_c + \vec{v}_{cm}$$

↓ 平功. → 转功.

$$\int \vec{v}_c \times \vec{B} \cdot d\vec{r}_m \rightarrow \frac{1}{2} \omega u (R^2 - r^2) B$$

$$= \vec{v}_c \times \vec{B} \cdot \int d\vec{r}_m$$

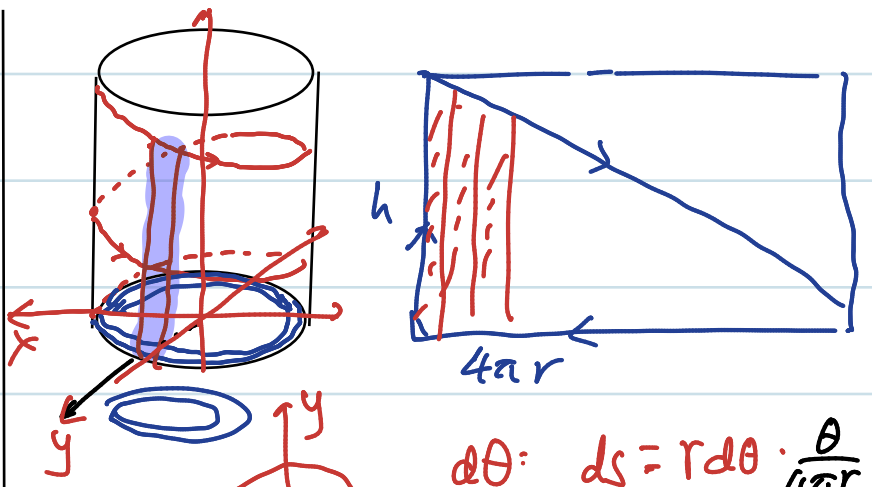
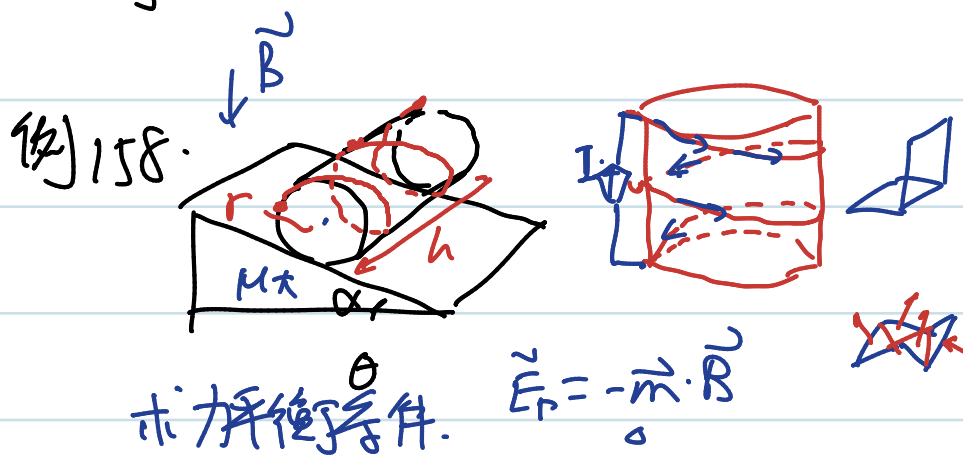
$$= u B (R+r)$$

$$\mathcal{E} = -\vec{B} \cdot \frac{\Delta \vec{S}}{\Delta t} = \frac{d\vec{B} \cdot \vec{m}}{dt I}$$

定电流

$$\frac{d\vec{B}}{dt} = 0$$

$\vec{J} = ?$



$$d\theta: ds = r d\theta \cdot \frac{\theta}{4\pi r} \cdot h$$

$$\hat{s} = (\cos \theta \hat{x} + \sin \theta \hat{y})$$

$$\vec{M}_{1R} = I \int_0^{4\pi} r \frac{\theta h}{4\pi r} (\cos \theta \hat{x} + \sin \theta \hat{y}) d\theta$$

$$= \int_0^{4\pi} \theta (\cos \theta \hat{x} + \sin \theta \hat{y}) d\theta$$

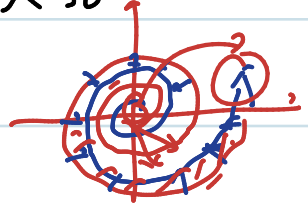
$$= \int_0^{4\pi} \theta e^{i\lambda \theta} d\theta$$

$$\int_0^{4\pi} e^{i\lambda \theta} d\theta = \frac{1}{i\lambda} e^{i\lambda \theta} \Big|_0^{4\pi}$$

$$= \frac{e^{i\lambda \theta} - 1}{i\lambda}$$

$$\frac{2}{\lambda} \int_0^{4\pi} e^{i\lambda \theta} d\theta = \int_0^{4\pi} i \theta e^{i\lambda \theta} d\theta = \frac{i \theta e^{i\lambda \theta}}{i\lambda} - \frac{e^{i\lambda \theta}}{i\lambda} \Big|_0^{4\pi}$$

$\lambda = 1$

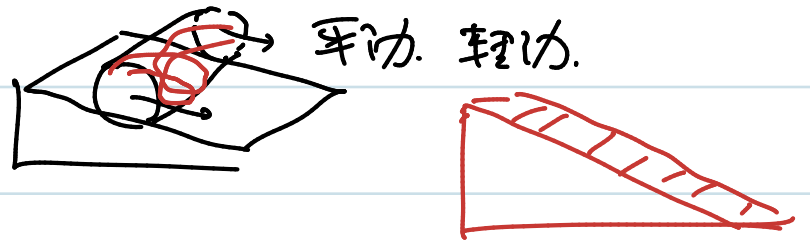


铁丝. 铁丝单位角质量相同

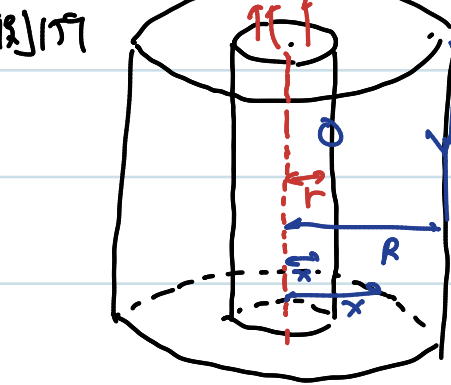
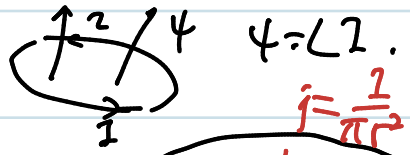
电源做功. $R \rightarrow \vec{m} \cdot \vec{B}$

$$\int u dq = \int u \frac{dq}{dt} dt = \int 2 d\psi$$

→ 板 [E] [A]



9.2 电感



单位长度电感

相对磁物

$$B(x) = \frac{\mu_0 \pi x j}{2\pi x}; x < R$$

$$B(x) = \frac{\mu_0 \pi R^2 j}{2\pi x}; R < x < l$$

按电流大小作加权平均。← 为什么

$$x \sim x+dx. dI = 2\pi x dx j$$

$$\frac{\psi(x)}{I} = \int_x^R B(z) \cdot dz$$

$$= \frac{\mu_0 j}{2} \left(\frac{R^2}{2} - \frac{x^2}{2} \right) + \frac{\mu_0 R^2 j}{2} \ln \frac{R}{x}$$

$$\frac{\psi_{\Sigma} I}{I} = \int_0^R \frac{\psi(x)}{I} dI$$

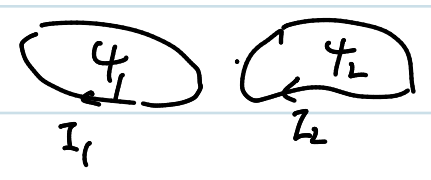
$$= \frac{\mu_0 j}{2} \int_0^R \left[\left(\frac{R^2}{2} - \frac{x^2}{2} \right) + \ln \frac{R}{x} \right] 2\pi x dx$$

$$\frac{\psi_{\Sigma} I}{I} = \frac{\mu_0 j}{2\pi r^2} \left[\frac{R^2 R}{2} - \frac{R^3}{6} + \ln \frac{R}{r} \cdot (R-r) \right]$$

电路 $dW = \int U dq$

$$= \int \psi \cdot \frac{dq}{dt} = \psi dI$$

例160. 互感



实际磁通

$$\psi_1(z_1, z_2) = a_{11} z_1 + a_{12} z_2$$

$$\psi_2(z_1, z_2) = a_{21} z_1 + a_{22} z_2$$

$$a_{12} = a_{21}$$

$$\psi = \int \vec{B} \cdot d\vec{s} = \int (\nabla \times \vec{A}) \cdot d\vec{s}$$

$$= \int \vec{A} \cdot d\vec{l} \Rightarrow \int \frac{\mu_0 d\vec{l}_1}{4\pi r} \cdot d\vec{l}_2$$

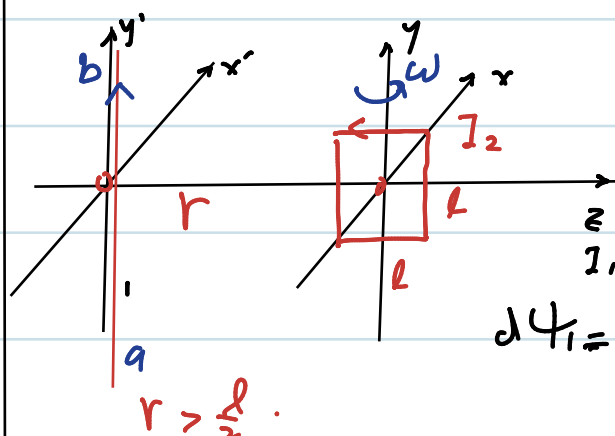
$$dW = \int (\psi_1 dI_1 + \psi_2 dI_2)$$

$$\int U_1 dI_1 + U_2 dI_2$$

$$\begin{cases} I_1 \rightarrow I_1 \rightarrow I_1 \\ I_2 \rightarrow I_2 \rightarrow I_2 \end{cases} \quad \begin{cases} I_1 \rightarrow I_1 \rightarrow I_1 \\ I_2 \rightarrow I_2 \rightarrow I_2 \end{cases}$$

$$a_{12} = a_{21}$$

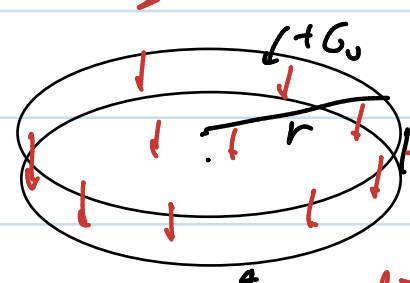
唯一性定理。W-标。 $a_{21} = a_{12}$



I_2 向 y 轴由以 ω 转动
求 $\epsilon_1 = ?$

$$d\psi_1 = L_1 \frac{dI_1}{dt} + M_{12} \frac{dI_2}{dt}$$

$$\times dM_{12} I_2$$



$$\frac{dM_{12}}{dt} = \frac{dM_{21}}{dt}$$

$$\epsilon = ?$$

$$r > l > h$$

电荷极 → 磁极假 $\Phi = \frac{\sigma \pi r^2 \cdot h}{\pi r^2} = \sigma h = E$

$$E \rightarrow B. \quad m \rightarrow B.$$

$$E = \frac{q}{4\pi \epsilon_0 r^2} \quad B = \frac{q_m \mu}{4\pi r^2}$$

$$\sigma h \rightarrow m \quad \vec{E} \rightarrow \vec{B}$$

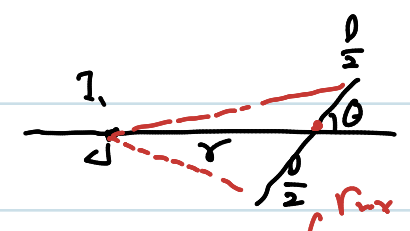
$$\frac{1}{\epsilon} \rightarrow \mu$$

$$l > h.$$

$$B = \frac{\mu_0 I \pi r^2}{2\pi l \pi r^2}$$

$$2\pi r^2 = m. \quad l < r$$

$$E = \frac{\mu_0 \pi r^2 \cdot \sigma h}{\epsilon_0 2\pi l \cdot \pi r^2}$$



$$M_{21} = \frac{\psi_2}{I_1}$$

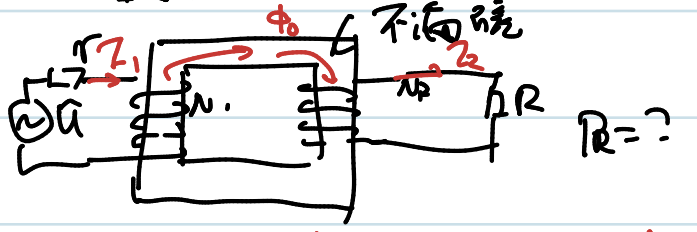
$$M_{21} = \frac{1}{I_1} \int_{r_{in}}^{r_{out}} l \cdot \frac{\mu_0 I_1}{2\pi s} ds$$

$$M_{21} = \frac{\mu_0}{2\pi} \cdot \ln \sqrt{\frac{r^2 + (\frac{l}{2})^2 + 2r \frac{l}{2} \cos \theta}{r^2 + (\frac{l}{2})^2 - 2r \frac{l}{2} \cos \theta}}$$

$$\epsilon_1 = \frac{dM_{21}}{dt} \cdot I_2$$

$$= I_2 \frac{\mu_0}{2\pi} \left[\frac{-2rl \sin \theta \omega}{r^2 + (\frac{l}{2})^2 + 2rl \cos \theta} - \frac{2rl \sin \theta \omega}{r^2 + (\frac{l}{2})^2 - 2rl \cos \theta} \right]$$

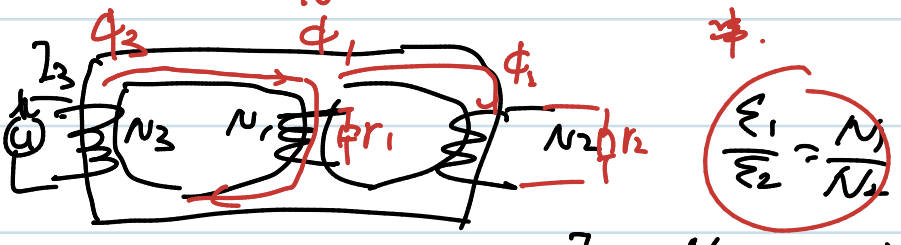
9.4 磁路



$\mathcal{E}_1 = N_1 \frac{d\Phi_0}{dt}$, $\mathcal{E}_2 = N_2 \frac{d\Phi_0}{dt}$, $\frac{\mathcal{E}_1}{\mathcal{E}_2} = \frac{N_1}{N_2}$

$\Delta E = 0$, $L_1 I_1 = L_2 I_2$

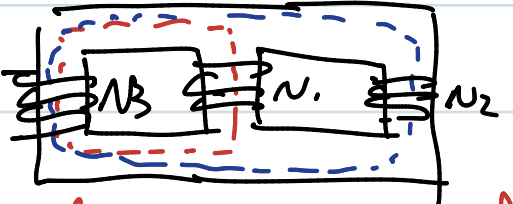
$\vec{U} = \vec{I}_1 r + \frac{N_1}{N_2} \vec{I}_2 r = \vec{I}_1 r + (\frac{N_1}{N_2} I_2) \vec{I}_1 R$



$\Phi_3 = \Phi_1 + \Phi_2$, $\frac{L_3}{L_2} = \frac{N_3}{N_2} \dots$

$\frac{\mathcal{E}_3}{N_3} = \frac{\mathcal{E}_1}{N_1} + \frac{\mathcal{E}_2}{N_2}$, $\mathcal{E}_3 L_3 = \mathcal{E}_1 L_1 + \mathcal{E}_2 L_2$

$\oint \vec{H} \cdot d\vec{l} = \sum I$, $\oint \vec{B} \cdot d\vec{s} = 0$, $\oint \vec{E} \cdot d\vec{l} = -\dot{\Phi}$, $\oint \vec{j} \cdot d\vec{s} = 0$



$B L \sim \frac{\Phi}{\mu} \cdot l \cdot \mu$

$\oint \vec{H} \cdot d\vec{l} = \sum I = \oint \frac{\vec{B}}{\mu_r \mu_0} \cdot d\vec{l}$

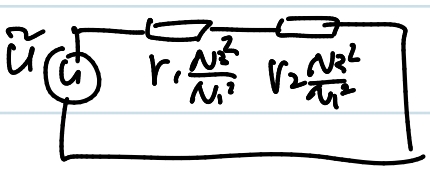
$\frac{\Phi \cdot l}{\mu_r \mu_0 N^2 S} = \sum I$, $\Phi \cdot R_m = \sum I$

不闭合磁路 $\mu_r \rightarrow \infty \Rightarrow R_m \rightarrow 0$, $\sum I \rightarrow 0$

$N_3 I_3 = N_1 I_1$, $N_3 I_3 = N_2 I_2$

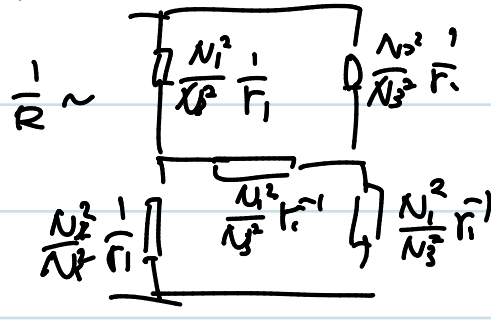
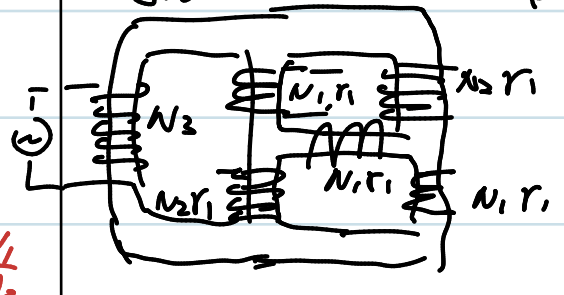
$\frac{\mathcal{E}_3}{N_3} = \frac{\mathcal{E}_1}{N_1} + \frac{\mathcal{E}_2}{N_2}$

$\mathcal{E}_3 = \frac{N_3}{N_1} \cdot I_1 r_1 + \frac{N_3}{N_2} r_2$
 $= \frac{N_3}{N_1} \cdot \frac{N_3}{N_1} I_1 r_1 + \frac{N_3}{N_1} \cdot \frac{N_3}{N_1} I_3 r_2$



例161

成功率 = ?

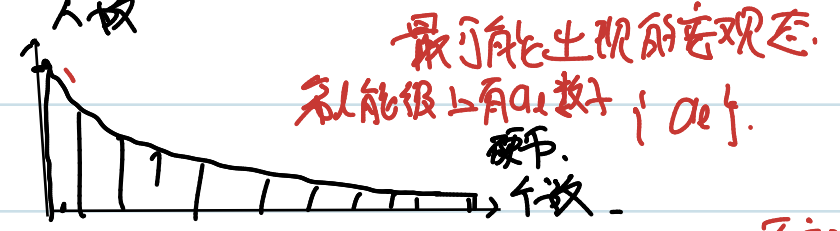


10. 建模 迁移类比

例162

有100个人, 每个人有100硬币. 每次随机硬币给一个人

如100, 硬币分布? 趋向于不均匀分布.



最可能出现的状态. 每个能级上有a_i个粒子.

硬币 → 能量, 人 → 粒子. $\sum N$ 不变, $\sum E$ 不变. 自由作用.

状态 M-B 分布. 最少硬币 → 级别. 一个能级上粒子数.

$\therefore \mathcal{E}_i: p_i = A e^{-\beta \mathcal{E}_i}$, $\beta = \frac{1}{kT}$

$\sum p_i = 1$, $\sum_{i=1}^N A e^{-\beta \mathcal{E}_i} = 1$

每个人有M个 \mathcal{E}_0 , $\sum_{i=1}^N A \cdot e^{-\beta i \mathcal{E}_0}$, $\mathcal{E}_0 = \bar{\mathcal{E}} = m \mathcal{E}$

A, β 定.

一个确定的硬币出现在一个确定的人上概率 $\frac{1}{N}$.

等概率.

{a_i} 定态 → (一个微状态概率) · 微状态个数

$(\frac{1}{N})^{N_{tot}}$, $\Omega\{a_i\}$

$\Omega\{a_i\} = C_N^{a_1} \cdot C_{N-a_1}^{a_2} \cdot C_{N-a_1-a_2}^{a_3} \dots C_{a_n}^{a_n}$

a_1, a_2, \dots 1-能级. $= \frac{N!}{a_1! (n-a_1)! a_2! (n-a_1-a_2)! \dots}$

$= \frac{N!}{\prod a_i!}$

$\ln \Omega = A - \sum \ln a_i!$ $\ln \Omega = A - \sum (a_i \ln a_i - a_i)$

$\ln \Omega = A - \sum (a_i \ln a_i - a_i)$ $S = k \ln \Omega$

改变 $\{a_i\}$ 使 $\ln \Omega \{a_i\}$ max. $S = -\sum n_i \ln n_i$

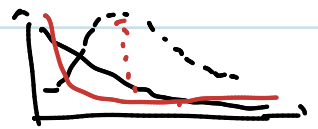
$\begin{cases} \sum a_i = N & (1) \\ \sum i a_i = Nm & (2) \end{cases}$ 可解最大熵

令 $S' = \ln \Omega + \alpha \sum a_i + \beta \sum i a_i$

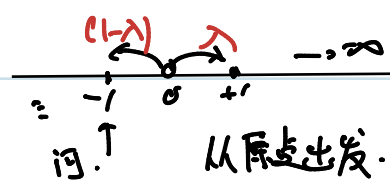
$\frac{\partial S'}{\partial a_i} = 0$ 拉格朗日乘数

$\Rightarrow -\ln a_i + \alpha + \beta \cdot i = 0$

$a_i = e^{-\alpha - \beta i}$ α, β 由 (1), (2) 定



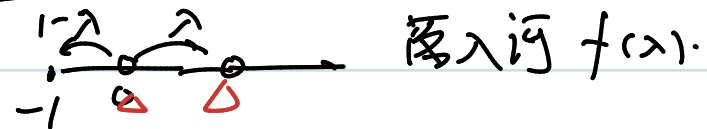
例.163. 随机游走



$P(x, t) = \lambda P(x-1, t-1) + (1-\lambda) P(x+1, t-1)$

$x \geq 1$
 $x=0$ $P(0, t) = (1-\lambda) P(1, t)$

$P(x, 0) = \begin{cases} 1 & x=0 \\ 0 & x \neq 0 \end{cases}$ 对时间 $t \rightarrow \infty$



$f(x) = (1-\lambda) + \lambda \cdot g(x)$
 $0 \rightarrow -1$ $\lambda + (1-\lambda) \cdot 2$

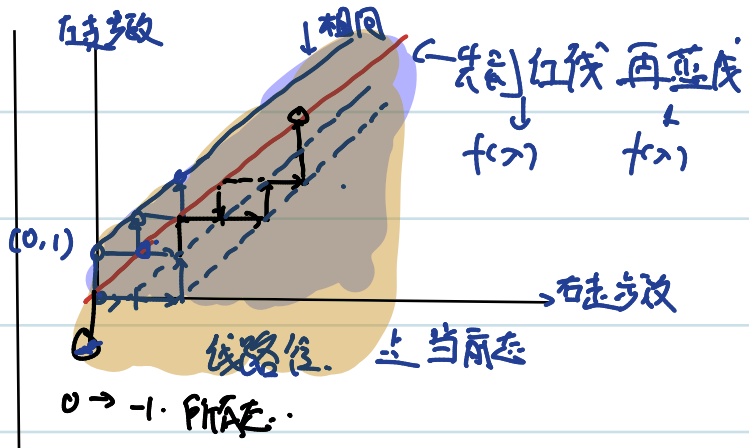
$g(x) = f(x) \cdot f(x)$ $0 \rightarrow -1$
 $-1 \rightarrow -2$ $-1 \rightarrow -2$

$f(x) = (1-\lambda) + \lambda f^2(x)$ 解得

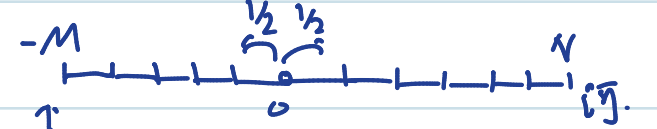
$\lambda f^2(x) - f(x) - (1-\lambda) = 0$

$(\lambda f(x) - (1-\lambda))(f(x) - 1) = 0$

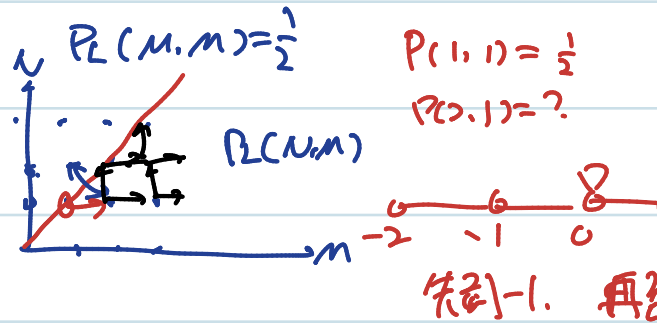
$f(x) = \begin{cases} 1 & \lambda < 1/2 \\ \frac{1-\lambda}{\lambda} & \lambda > 1/2 \end{cases}$



$0 \rightarrow -1$ $P_L(M, N) = ?$
 $0 \rightarrow -2$



$P_L(M, N) + P_R(M, N) = 1$
 $P_L(M, N) = P_L(N, M)$



$P_L(M, M) = \frac{1}{2}$ $P(1, 1) = \frac{1}{2}$
 $P(2, 1) = ?$

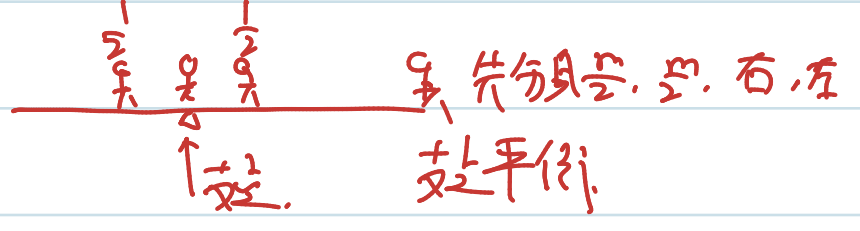
$P_L(2, 1) = P_L(1, 1) \cdot [\frac{1}{2} + \frac{1}{2} P_L(2, 1)]$
解得: $P_L(2, 1) = \frac{1}{3}$ $P_L(1, 2) = \frac{2}{3}$



$P_L(3, 1) = P_L(2, 1) (\frac{1}{2} + P_L(2, 2))$ $P_L(3, 1) = \frac{1}{4}$

$P_L(4, 1) = P_L(3, 1) (\frac{1}{2} + P_L(2, 3))$ 递推方程解

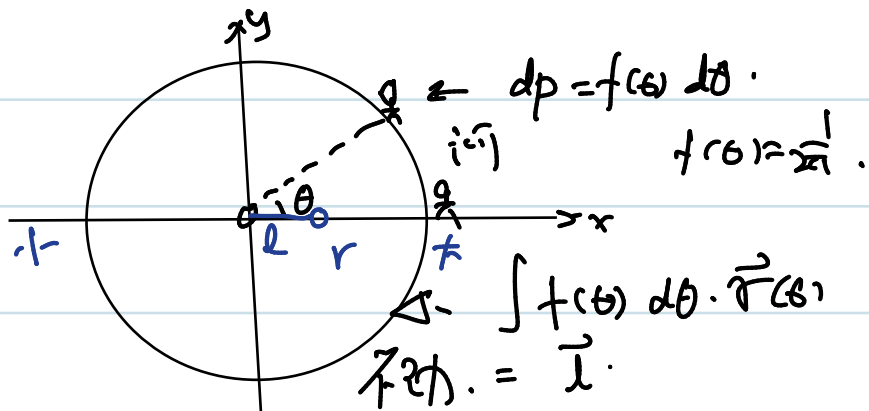
$P_L(M, N) = \frac{N}{M+N}$ 再作一次



再走一次. 支点平衡. (平衡不动. 平衡)

最后:
 $P_L(M, N) \cdot M = P_R(M, N) \cdot N$ 杠杆平衡
 $\Rightarrow P_L(M, N) = \frac{N}{M+N}$

二维流注



$f(x, y, t) dx dy$ $r < r, r$

$\Delta t \frac{\partial f}{\partial t}(x, y, t) = -f + \frac{1}{4} f(x+1, y, t-1)$

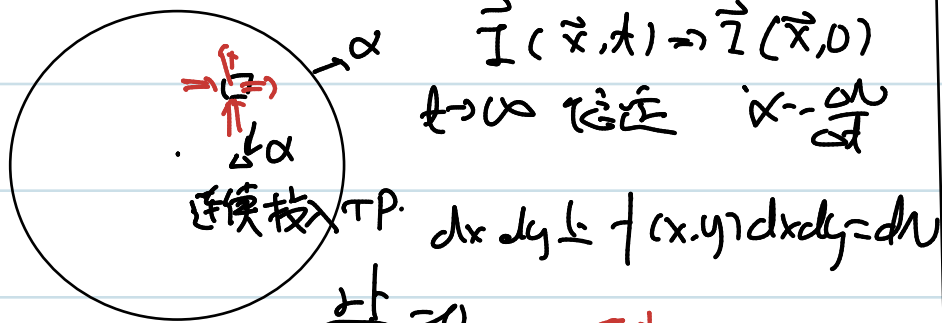
$+ \frac{1}{4} f(x-1, y, t-1) + \frac{1}{4} f(x, y+1, t-1) + \frac{1}{4} f(x, y-1, t-1)$

\Rightarrow (微分) $\frac{\partial f}{\partial t} = \frac{1}{\Delta t} \left(\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} \right)$

$\frac{\partial f}{\partial t} = D \nabla^2 f$ 扩散

这时. 要求只是 $t \rightarrow \infty$ 时平均

在时间轴上平铺



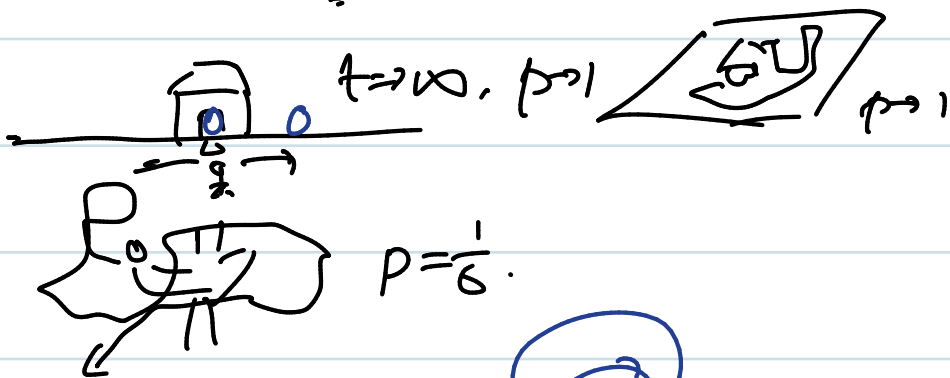
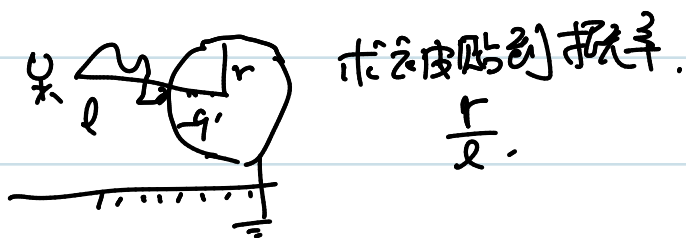
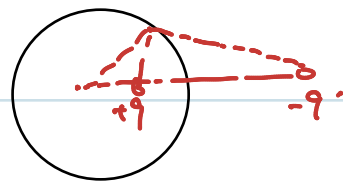
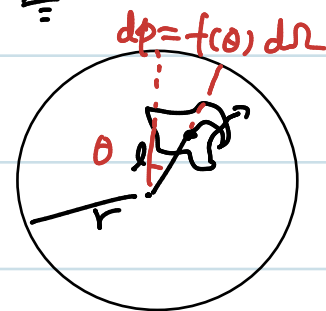
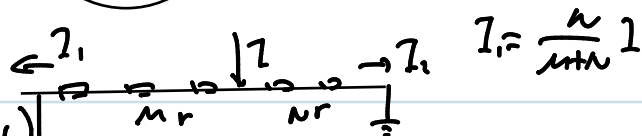
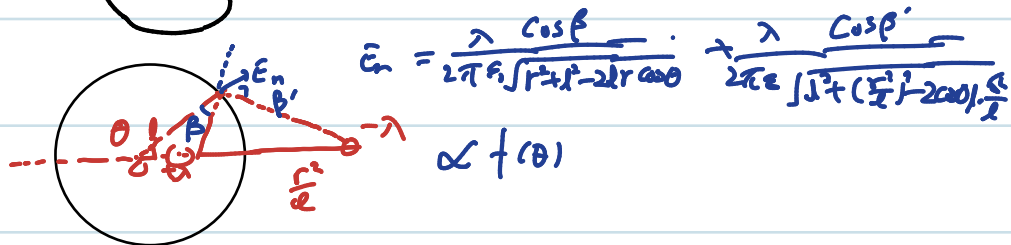
$\Delta t = \lambda \left[\frac{1}{4} f(x-\Delta x, y) - \frac{1}{4} f(x, y) \right] \Delta y$
 $+ \left[\frac{1}{4} f(x, y-\Delta y) - \frac{1}{4} f(x, y) \right] \Delta x$
 $+ \left[\frac{1}{4} f(x+\Delta x, y) - \frac{1}{4} f(x, y) \right] \Delta y$
 $+ \left[\frac{1}{4} f(x, y+\Delta y) - \frac{1}{4} f(x, y) \right] \Delta x$
 $= \omega x \cdot \omega y \cdot \Delta t^2 f$

浓度 $f \rightarrow$ 电势

$\nabla f \rightarrow$ 电流

$\nabla \cdot \nabla f \rightarrow$ 电荷变化 $\rightarrow 0$

$\nabla^2 \psi = 0$



还存

每条长 L . 数 S . $V = nSL$

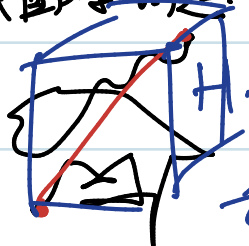


每根纤维与多少根纤维接触

$$N(L) = AL^\alpha. \text{ 取 } \alpha = ?$$

$$\text{数 } \hat{n}(s) \rightarrow \hat{n}(s+l) \text{ 数 } \overline{\hat{n}(s) \cdot \hat{n}(s+l)} = 0$$

面形状态 \Rightarrow 随机走的人



$$\vec{H} = 0 \quad \overline{H^2} \neq 0$$

每 N 步.

$$\overline{H_N^2} = \overline{(\vec{H}_{N-1} + l \cdot \hat{n})^2} \quad \text{0 数}$$
$$= \overline{H_{N-1}^2} + l^2 + \overline{2 \vec{H}_{N-1} \cdot \hat{n} l}$$

$$\overline{H_N^2} = Nl^2 \cdot \sqrt{\overline{H_N^2}} = \sqrt{N} l.$$

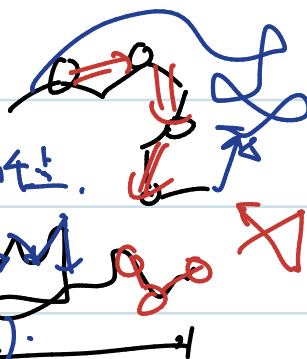
在 H 的体积中面形有随单位根纤维接触

$$V \propto \sqrt{H_N^2}^3. \text{ 接触数 } \propto V \cdot n.$$

$$= N^{3/2} \cdot n = L^{3/2} \cdot n$$

走 N 步

高分子. 状态 \Rightarrow 随机游走



平均大小 $\propto N^{1/2}$

高分子档住自己

长度为 l 的态出现概率.

$\Omega_l \leftarrow$ 长 l 微状态数.



$$\Omega(l, N) = \int \Omega(l + l\hat{n}, N-1) \cdot \frac{d\Omega}{4\pi}$$

$$= \int \left[\Omega(l) + \Omega(l) \cdot l\hat{n} + \frac{1}{2} l^2 \hat{n} \hat{n} \Omega(l) \right] \frac{d\Omega}{4\pi}$$

Ω 扩散方程

$$= \Omega(l) \Omega(l, N-1)$$

$$\Omega_l \propto B e^{-Al^2}$$

$$\frac{\pi(1 - m \cdot n \cdot l^6)}{m} \sim \text{随机}$$

$$L \cdot e^{-\frac{1}{2} N l^2}$$